

Lagrangian Bias in the Local Bias Model

Noemi Frusciante

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Normalizing density rather than overdensity Renormalized

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Lagrangian Bias in the Local Bias Model

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In Collaboration with Ravi K. Sheth (in preparation)

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Outline

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An important part of Cosmology is the Large Scale Structure, today numerical simulations/observations allow us to test

- The formation/evolution of structures
- Initial spectrum
- Biasing
- Dark Energy models (among which Modified Gravity Models)
- Whatever other parameters come into describing the Universe

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In modelling the structures' clustering a crucial step is to understand how the spatial distribution of galaxies is related to the underlying (dark) matter distribution

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- \bullet Light does not trace the mass \to BIAS
- The matter distribution is highly clustered



Springel et al. (2005)

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Define the dimensionless density perturbation field $\delta(\bar{x}) = \frac{\rho(\bar{x}) - \bar{\rho}}{\bar{\rho}}$

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Bias types:

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- Stochastic $\delta_b \neq b \langle \delta_b | \delta_m \rangle$

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REAL BIAS is non-linear, stochastic and quite deterministic see Dekel & Lahav (1999), Sheth & Lemson 1999, Tegmark & Bromley (1999)

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• GR: Halo mass bias from cross power spectra



Manera, Sheth & Scoccimarro (2010)

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Manera, Sheth & Scoccimarro (2010)

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• $k < 0.05h^{-1}$ Mpc k-independent \rightarrow the bias in Fourier space is related (equal to) those in configuration space



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- $k < 0.05h^{-1}$ Mpc k-independent \rightarrow the bias in Fourier space is related (equal to) those in configuration space
- at larger k strong k-dependence



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- MG: The bias depends on scale also at small k:



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- at larger k strong k-dependence
- MG: The bias depends on scale also at small k:
 - D(k,t)
 - Curved barrier: $\delta_{sc}(m(R_s))$



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• Introduced by Fry & Gaztãnaga (1993)

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• Introduced by Fry & Gaztãnaga (1993)

• Assumptions: non linear, local and deterministic $\delta_b = f[\delta_m]$

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- Assumptions: non linear, local and deterministic $\delta_b = f[\delta_m]$

The Model

On large enough smoothing scales, where the fluctuations are small, this relation can be expanded in a Taylor series

$$\delta_b = f(\delta_m) = \sum_{i>0} \frac{b_i}{i!} (\delta_m^i - \langle \delta_m^i \rangle),$$

Note that this model ensures $\langle \delta_b \rangle = 0$ by subtracting-off the $\langle \delta_m^i \rangle$ terms.



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Note that this model ensures $\langle \delta_b \rangle = 0$ by subtracting-off the $\langle \delta_m^i \rangle$ terms.

• It is used to describe the bias with respect to the Eulerian field BUT it is often assumed to describe the bias with respect to the initial Lagrangian field: δ_L .



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• PROBLEM: The cross correlation between the biased tracers and the initial field involves higher order terms

$$\langle \delta_b \delta_L \rangle = \sum_{k>0} \frac{b_k}{k!} \langle \delta_L^{k+1} \rangle$$

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• PROBLEM: The cross correlation between the biased tracers and the initial field involves higher order terms

$$\langle \delta_b \delta_L \rangle = \sum_{k>0} \frac{b_k}{k!} \left\langle \delta_L^{k+1} \right\rangle$$

• We expect (e.g. Peaks and Patches which forms halos)

$$\langle \delta_b \delta_L \rangle = b \langle \delta_L^2 \rangle$$

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The correctly normalized bias field is defined by

SOLUTION

$$\delta_B \equiv \frac{1 + \delta_b - \langle 1 + \delta_b \rangle}{\langle 1 + \delta_b \rangle} = \frac{\sum_{k=1}^{\infty} (b_k/k!) (\delta_L^k - \langle \delta_L^k \rangle)}{\sum_{k=0}^{\infty} (b_k/k!) \langle \delta_L^k \rangle}$$

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• The cross correlation is

$$\langle \delta_{L'} \delta_B | r \rangle = \xi_{LL'}(r) \frac{\sum_{k=1}^{\infty} (b_k/k!) \langle \delta_L^{k+1} \rangle / \langle \delta_L^2 \rangle}{\sum_{k=0}^{\infty} (b_k/k!) \langle \delta_L^k \rangle} \equiv \xi_{LL'}(r) B_L,$$

Note: this is an exact statement, valid for any r, L or L', and for any local deterministic bias function.



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Note: this is an exact statement, valid for any r, L or L', and for any local deterministic bias function.

• The auto-correlation function of the biased tracers will reduce to a series of the form [Similar result by Szalay (1988)]

$$\langle \delta_{B'} \delta_B | r \rangle = B_L^2 \xi_{LL}(r) + \frac{C_L}{2} [\xi_{LL}(r)]^2 + \dots$$



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What do you do when this cannot be done analytically?

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What do you do when this cannot be done analytically?

Mc Donald (2006) suggests redefining the mean density, and hence all bias factors order by order

$$\delta_B^{(j)} = \frac{1 + \delta_b - \langle 1 + \delta_b \rangle_j}{\langle 1 + \delta_b \rangle_j} = \frac{\sum_{k=1}^j (b_k/k!) (\delta_L^k - \langle \delta_L^k \rangle)}{\sum_{k=0}^j (b_k/k!) \langle \delta_L^k \rangle}$$

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• The cross-correlation between the mass and biased fields is

$$\langle \delta_{L'} \delta_{B}^{(j)} | r \rangle = rac{\sum_{k=1}^{j} (b_k/k!) \langle \delta_{L}^k \delta_{L} | r \rangle}{\sum_{k=0}^{j} (b_k/k!) \langle \delta_{L}^k
angle}.$$

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angle = rac{\sum_{k=1}^j (b_k/k!) \langle \delta_L^k \delta_L | r
angle}{\sum_{k=0}^j (b_k/k!) \langle \delta_L^k
angle}.$$

• To 4th order in δ_L , this is

$$\langle \delta_{L'} \delta_B^{(4)} | r \rangle = \left[b_1 + \left(\frac{b_3}{2} - \frac{b_1 b_2}{2} \right) \langle \delta_L^2 \rangle \right] \xi_{LL'}(r) \equiv b_{\times}^{(4)} \xi_{LL'}(r)$$

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The Bias coefficient is defined

$$b^{(4)}_{ imes}\equiv b_1+\left(rac{b_3}{2}-rac{b_1b_2}{2}
ight)\,\langle\delta^2_L
angle$$

Note: The Cross-correlation does not include higher order terms !

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• Lognormal field : $1 + \delta_b = \exp(b\delta_L) \exp(-b^2 \langle \delta_L^2 \rangle/2)$

$$b_3=b_1b_2 \hspace{0.1in}
ightarrow \hspace{0.1in} b_{ imes}^{(4)}\equiv b_1=B_L$$

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Note: The Cross-correlation does not include higher order terms ! Examples:

• Lognormal field : $1 + \delta_b = \exp(b\delta_L) \exp(-b^2 \langle \delta_L^2 \rangle/2)$

$$b_3 = b_1 b_2 \quad o \quad b_{ imes}^{(4)} \equiv b_1 = B_L$$

• Peaks :
$$1 + \delta_p = \exp(b\delta_L - c\delta_L^2/2)\sqrt{1 + c\langle\delta_L^2\rangle} \exp\left(-\frac{b^2\langle\delta_L^2\rangle/2}{1 + c\langle\delta_L^2\rangle}\right)$$

$$b_3
eq b_1 b_2 \quad o \quad b_{ imes}^{(4)} = b ig(1 - c \langle \delta_L^2
angle ig) \quad o \quad B_L = rac{b}{1 + c \langle \delta_L^2
angle}$$



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Assuming that the Lagrangian bias is local and deterministic with respect to the initial Gaussian field, we showed that with a CORRECT NORMALIZATION

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Assuming that the Lagrangian bias is local and deterministic with respect to the initial Gaussian field, we showed that with a CORRECT NORMALIZATION

• The two point cross-correlation between the tracer and mass is always only linearly proportional to the auto-correlation signal of the DM.

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- The two point cross-correlation between the tracer and mass is always only linearly proportional to the auto-correlation signal of the DM.
- The auto correlation function of locally biased tracers can be written as a Taylor series in the auto-correlation function of the mass.



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- The two point cross-correlation between the tracer and mass is always only linearly proportional to the auto-correlation signal of the DM.
- The auto correlation function of locally biased tracers can be written as a Taylor series in the auto-correlation function of the mass.
- These relations allow for simple tests of whether or not halo bias is indeed local in Lagrangian space.

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- The two point cross-correlation between the tracer and mass is always only linearly proportional to the auto-correlation signal of the DM.
- The auto correlation function of locally biased tracers can be written as a Taylor series in the auto-correlation function of the mass.
- These relations allow for simple tests of whether or not halo bias is indeed local in Lagrangian space.
- Our results should also hold for MG models. Of course, for MG, it is not obvious that the assumption that the Lagrangian bias should be local is a good one (needs to be tested).