

ROTATING FIGURES OF EQUILIBRIUM

NEB XV

In the context of Newtonian theory of Gravitation

- The study of the shape of a rotating homogeneous mass ,with uniform velocity has been carried out by some of the greatest scientists :
- I) Newton (Principia, Book III, Proposition XVIII-XX), small eccentricity.
- II) Maclaurin ,the eccentricity is not small
Maclaurin Spheroids (1742)

- III) Jacobi, (1834) , triaxial ellipsoids
- IV) Meyer and Liouville (1842,1846) relation between Maclaurin spheroids and Jacobi ellipsoids ,no figures of equilibrium are possible when the angular velocity exceeds a limit.
- V) Dirichlet, Dedekind, Riemann (1892)
Dirichlet (in a Lagrangian framework) and Dedekind working on the paper of Dirichlet defined the ellipsoids of Dirichlet. Riemann gave a complete solution for the stationary figures of equilibrium.
- VI) Poincare(1885), Cartan (1924)
Stability of ellipsoids figures of equilibrium, (pear shaped configurations), stability of Jacobi ellipsoids

Details and the continuation of the story in :

“Ellipsoidal Figures of Equilibrium” by S Chandrasekhar

In the context of General Relativity

- Problem
Find all possible equilibrium interior configurations, satisfying Einstein's equations, bounded by a surface of zero hydrostatic pressure, matched across this surface to a vacuum solution, sharing the same symmetries: stationarity and axial symmetry.

- We suppose that the space admits an isometry Abelian group invertible, with non null surface of transitivity

$$ds^2 = g_{tt} dt^2 + 2g_{tz} dt dz + g_{zz} dz^2 - g_{xx} dx^2 - g_{yy} dy^2$$

- The components of the metric tensor depend only on x and y , the group is generated by $\frac{\partial}{\partial t}$ (time-like Killing vector, implying the stationarity) and $\frac{\partial}{\partial z}$ (space-like Killing vector, implying the axial symmetry)

Symmetric null tetrad and Carter's metric [A]

$$ds^2 = (Ldt + Mdz)^2 - (Ndt + Pdz)^2 - S^2 dx^2 - R^2 dy^2$$

, L, M, N, P are functions of x and y

$$ds^2 = (x^2 + y^2) \left\{ \frac{E^2(y)}{(x^2 + y^2)^2} (dt - x^2 dz)^2 - \frac{H^2(x)}{(x^2 + y^2)^2} (dt + y^2 dz)^2 - \frac{x^2 dx^2}{F^2(x)} - \frac{y^2 dy^2}{G^2(y)} \right\}$$

Kerr and Whalquist metrics

$$G^2(y) = y^2 E^2(y)$$

$$F^2(x) = x^2 H^2(x)$$

$$E^2(y) = \frac{1}{2}by^2 + dy + p$$

$$H^2(x) = -\frac{1}{2}bx^2 + cx + p$$

$$b = 2 \quad d = -2m$$

$$c = 0 \quad p = a^2$$

$$y = r$$

$$x = a \cos \theta$$

Whalquist metric

e+3p=constant

$$W(y) = \frac{G^2(y)}{E^2(y)} = k_4 y^4 + k_2 y^2 - k_0$$

$$Z(x) = \frac{F^2(x)}{H^2(x)} = -k_4 x^4 + k_2 x^2 + k_0$$

Surfaces of revolution

- We consider three dimensional Euclidean space foliated with surfaces of revolution with centre O and common axis of rotation L . Each surface is obtained by revolving a plane curve C about the axis of rotation L , this axis coincides with the axis of rotation of the fluid configuration. In a Cartesian coordinate system, the curve C lies in the plane and is the axis of revolution. In this coordinate system, a parametric representation of the curve C is defined as follows:

Parametric representation of a surface of revolution

$$x_1 = h_1(t) \cos \Phi \quad x_2 = h_1(t) \sin \Phi \quad x_3 = h_2(t)$$

$$x_1 = h_1(r, \theta) \cos(\Phi), x_2 = h_2(r, \theta) \sin(\Phi), x_3 = r \cos(\theta)$$

$$ds_3^2 = (h_{1r}^2 + \cos^2(\theta))^2 dr^2 + (h_{1\theta}^2 + r^2 \sin^2(\theta)^2) d\theta^2 + h_1^2 d\Phi^2 + 2(h_{1r} h_{1\theta} - r \sin(\theta) \cos(\theta)) dr d\theta$$

$$h_{1\theta} = \frac{\partial h_1}{\partial \theta}$$

Euclidean and Riemannian metrics

$$ds_3^2 = \frac{[a^2 h_{1r}^2 + \cos(\theta)^2]}{f^2(r, \theta)} dr^2 + [h_{1\theta}^2 + r^2 \sin(\theta)^2] d\theta^2 + h_1^2 d\Phi^2$$

$f(r, \theta) = 1$ *Euclidean*

$$y = r \quad x = a \cos(\theta)$$

$$ds_3^2 = \frac{[a^2 h_{1y}^2 + x^2]}{a^2 f^2(x, y)} dy^2 + [a^2 h_{1x}^2 + y^2] dx^2 + h_1^2 d\Phi^2$$

Quotient space of the comoving observers

$$u = u^i \frac{\partial}{\partial x^i} = U(x, y) \frac{\partial}{\partial t} + V(x, y) \frac{\partial}{\partial z} \quad u_i u^i = 1$$

$$ds_3^2 = \frac{[a^2 h_{1y}^2 + x^2]}{a^2 f^2(x, y)} dy^2 + [a^2 h_{1x}^2 + y^2] dx^2 + h_1^2 d\Phi^2 = g_{ij} dx^i dx^j - u_i u_j dx^i dx^j$$

$$\frac{[a^2 h_{1y}^2 + x^2]}{a^2 f^2} = g_{yy}, \quad \frac{[a^2 h_{1x}^2 + y^2]}{a^2} = g_{xx}, \quad V^2 [g_{t\varphi}^2 - g_{tt} g_{\varphi\varphi}] = h_1^2 \quad dt - \frac{U}{V} d\varphi = d\Phi$$

$$\varphi = az$$

Carter's family [A]

$$ds^2 = (x^2 + y^2) \left\{ \frac{E^2(y)}{(x^2 + y^2)^2} (dt - x^2 dz)^2 - \frac{H^2(x)}{(x^2 + y^2)^2} (dt + y^2 dz)^2 - \frac{x^2 dx^2}{F^2(x)} - \frac{y^2 dy^2}{G^2(y)} \right\}$$

$$\frac{[a^2 h_{1y}^2 + x^2]}{a^2 f^2} = (x^2 + y^2) \frac{y^2}{G^2}$$

$$\frac{[a^2 h_{1x}^2 + y^2]}{a^2} = (x^2 + y^2) \frac{x^2}{F^2}$$

$$V^2 E^2 H^2 = a^2 h_1^2$$

$$a^2 h_{1y} h_{1x} + xy = 0$$

The surface of revolution is completely defined

$$V = e_1 \frac{h_1 a}{EH} \quad e_1 = \pm 1 \quad e_2 = \pm 1$$

$$U = \frac{1}{E^2 - H^2} \left\{ e_1 \frac{(x^2 E^2 + y^2 H^2)}{EH} h_1 + e_2 [(x^2 + y^2)(E^2 - H^2) + h_1^2 (x^2 + y^2)^{\frac{1}{2}}] \right\}$$

$$h_1 = -\frac{1}{a} (a^2 - x^2)^{\frac{1}{2}} (a^2 + y^2)^{\frac{1}{2}} + g$$

$$F^2 = x^2 (a^2 - x^2) \quad \frac{G^2}{f^2} = y^2 (a^2 + y^2)$$

Two possible cases

(I)

$$g = 0 \quad \frac{x_1^2 + x_2^2}{a^2 + r^2} + \frac{x_3^2}{r^2} = 1$$

Krasinski 1978

(II)

$$g \neq 0 \quad \text{tori of revolution} \quad \frac{(x_1 - g)^2}{a^2 + r^2} + \frac{x_3^2}{r^2} = 1$$

Perfect fluid with heat flux

$$T_{ij} = (e + p)u_i u_j - p g_{ij} + q_i u_j + q_j u_i$$

$$2[x^3 y(x^2 + y^2)^2] W E_{y,y}^2 + (x^2 + y^2) [-2x^3(5y^2 + x^2)W + x^3 y(x^2 + y^2)W_y] E_y^2 +$$

$$+ 8x^3 y^3 (W + Z) E^2 -$$

$$- 2[xy^3(x^2 + y^2)^2] Z H_{xx}^2 - (x^2 + y^2) [-2y^3(5x^2 + y^2)Z + xy^3(x^2 + y^2)Z_x] H_x^2 -$$

$$- 8x^3 y^3 (W + Z) H^2 = 0$$

$$W = \frac{G(y)}{E(y)}$$

$$Z = \frac{F(x)}{H(x)}$$

Solution

$$W = kE^2 + k_4 y^4 + k_2 y^2 + k_0$$

$$Z = kH^2 + l_4 x^4 + l_2 x^2 + l_0$$

$$H^2 = \frac{a^2(a^2 - x^2)}{k_0 - a^2 k_2}$$